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Строк надруку: 4 стор.
На основі: сувоя варіанта

THE UNIVERSITY OF CHICAGO PRESS

Делна форма на вярта

THE UNITED STATES DEPARTMENT OF THE INTERIOR
BUREAU OF LAND MANAGEMENT
WASHINGTON, D. C. 20246

1. $\mathcal{H} = \{H_1, H_2, \dots, H_n\}$ is a set of n hypotheses, where H_i is a hypothesis that the system is in state i .
2. $\mathcal{O} = \{O_1, O_2, \dots, O_m\}$ is a set of m observations, where O_j is an observation that the system is in state j .
3. $\mathcal{A} = \{A_1, A_2, \dots, A_k\}$ is a set of k actions, where A_l is an action that the system can take.
4. $\mathcal{C} = \{C_1, C_2, \dots, C_p\}$ is a set of p costs, where C_q is a cost that the system incurs when it takes an action.
5. $\mathcal{P} = \{P_1, P_2, \dots, P_r\}$ is a set of r probabilities, where P_s is a probability that the system transitions from one state to another.
6. $\mathcal{R} = \{R_1, R_2, \dots, R_t\}$ is a set of t rewards, where R_u is a reward that the system receives when it takes an action.
7. $\mathcal{S} = \{S_1, S_2, \dots, S_v\}$ is a set of v states, where S_w is a state that the system can be in.
8. $\mathcal{D} = \{D_1, D_2, \dots, D_z\}$ is a set of z decisions, where D_y is a decision that the system can make.
9. $\mathcal{E} = \{E_1, E_2, \dots, E_x\}$ is a set of x events, where E_v is an event that the system can experience.
10. $\mathcal{F} = \{F_1, F_2, \dots, F_y\}$ is a set of y features, where F_w is a feature that the system can have.
11. $\mathcal{G} = \{G_1, G_2, \dots, G_z\}$ is a set of z goals, where G_u is a goal that the system can achieve.
12. $\mathcal{I} = \{I_1, I_2, \dots, I_x\}$ is a set of x inputs, where I_v is an input that the system can receive.
13. $\mathcal{J} = \{J_1, J_2, \dots, J_y\}$ is a set of y outputs, where J_w is an output that the system can produce.
14. $\mathcal{K} = \{K_1, K_2, \dots, K_z\}$ is a set of z keys, where K_u is a key that the system can use.
15. $\mathcal{L} = \{L_1, L_2, \dots, L_x\}$ is a set of x labels, where L_v is a label that the system can assign.
16. $\mathcal{M} = \{M_1, M_2, \dots, M_y\}$ is a set of y models, where M_w is a model that the system can use.
17. $\mathcal{N} = \{N_1, N_2, \dots, N_z\}$ is a set of z names, where N_u is a name that the system can use.
18. $\mathcal{O} = \{O_1, O_2, \dots, O_x\}$ is a set of x objects, where O_v is an object that the system can interact with.
19. $\mathcal{P} = \{P_1, P_2, \dots, P_y\}$ is a set of y parameters, where P_w is a parameter that the system can adjust.
20. $\mathcal{Q} = \{Q_1, Q_2, \dots, Q_z\}$ is a set of z quantities, where Q_u is a quantity that the system can measure.
21. $\mathcal{R} = \{R_1, R_2, \dots, R_x\}$ is a set of x results, where R_v is a result that the system can achieve.
22. $\mathcal{S} = \{S_1, S_2, \dots, S_y\}$ is a set of y sequences, where S_w is a sequence that the system can generate.
23. $\mathcal{T} = \{T_1, T_2, \dots, T_z\}$ is a set of z times, where T_u is a time that the system can measure.
24. $\mathcal{U} = \{U_1, U_2, \dots, U_x\}$ is a set of x units, where U_v is a unit that the system can use.
25. $\mathcal{V} = \{V_1, V_2, \dots, V_y\}$ is a set of y values, where V_w is a value that the system can calculate.
26. $\mathcal{W} = \{W_1, W_2, \dots, W_z\}$ is a set of z weights, where W_u is a weight that the system can assign.
27. $\mathcal{X} = \{X_1, X_2, \dots, X_x\}$ is a set of x variables, where X_v is a variable that the system can manipulate.
28. $\mathcal{Y} = \{Y_1, Y_2, \dots, Y_y\}$ is a set of y variables, where Y_w is a variable that the system can manipulate.
29. $\mathcal{Z} = \{Z_1, Z_2, \dots, Z_z\}$ is a set of z variables, where Z_u is a variable that the system can manipulate.
30. $\mathcal{A} = \{A_1, A_2, \dots, A_x\}$ is a set of x variables, where A_v is a variable that the system can manipulate.
31. $\mathcal{B} = \{B_1, B_2, \dots, B_y\}$ is a set of y variables, where B_w is a variable that the system can manipulate.
32. $\mathcal{C} = \{C_1, C_2, \dots, C_z\}$ is a set of z variables, where C_u is a variable that the system can manipulate.
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35. $\mathcal{F} = \{F_1, F_2, \dots, F_z\}$ is a set of z variables, where F_u is a variable that the system can manipulate.
36. $\mathcal{G} = \{G_1, G_2, \dots, G_x\}$ is a set of x variables, where G_v is a variable that the system can manipulate.
37. $\mathcal{H} = \{H_1, H_2, \dots, H_y\}$ is a set of y variables, where H_w is a variable that the system can manipulate.
38. $\mathcal{I} = \{I_1, I_2, \dots, I_z\}$ is a set of z variables, where I_u is a variable that the system can manipulate.
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44. $\mathcal{O} = \{O_1, O_2, \dots, O_z\}$ is a set of z variables, where O_u is a variable that the system can manipulate.
45. $\mathcal{P} = \{P_1, P_2, \dots, P_x\}$ is a set of x variables, where P_v is a variable that the system can manipulate.
46. $\mathcal{Q} = \{Q_1, Q_2, \dots, Q_y\}$ is a set of y variables, where Q_w is a variable that the system can manipulate.
47. $\mathcal{R} = \{R_1, R_2, \dots, R_z\}$ is a set of z variables, where R_u is a variable that the system can manipulate.
48. $\mathcal{S} = \{S_1, S_2, \dots, S_x\}$ is a set of x variables, where S_v is a variable that the system can manipulate.
49. $\mathcal{T} = \{T_1, T_2, \dots, T_y\}$ is a set of y variables, where T_w is a variable that the system can manipulate.
50. $\mathcal{U} = \{U_1, U_2, \dots, U_z\}$ is a set of z variables, where U_u is a variable that the system can manipulate.
51. $\mathcal{V} = \{V_1, V_2, \dots, V_x\}$ is a set of x variables, where V_v is a variable that the system can manipulate.
52. $\mathcal{W} = \{W_1, W_2, \dots, W_y\}$ is a set of y variables, where W_w is a variable that the system can manipulate.
53. $\mathcal{X} = \{X_1, X_2, \dots, X_z\}$ is a set of z variables, where X_u is a variable that the system can manipulate.
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64. $\mathcal{I} = \{I_1, I_2, \dots, I_y\}$ is a set of y variables, where I_w is a variable that the system can manipulate.
65. $\mathcal{J} = \{J_1, J_2, \dots, J_z\}$ is a set of z variables, where J_u is a variable that the system can manipulate.
66. $\mathcal{K} = \{K_1,$

III. $\lim_{n \rightarrow \infty} \frac{1}{n} \log \frac{1}{n} \sum_{i=1}^n \frac{1}{i} = 0$ and $\lim_{n \rightarrow \infty} \frac{1}{n} \log \frac{1}{n} \sum_{i=1}^n \frac{1}{i^2} = 0$.

III. PRAKTIKA

IV. EFFECTS

Наименование	Формат	Ссылка
<u>Алгоритм расчета</u>	Анализ	8

У. ПЛАН НАВЧАЛЬНОГО ПРОЦЕСУ

№	Назва освітньої компоненти	код кафедр	Розподіл за семестрами				ECTS	Залишилось кредитів ECTS	Кількість годин						Відсоток аудиторних занять																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																									
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